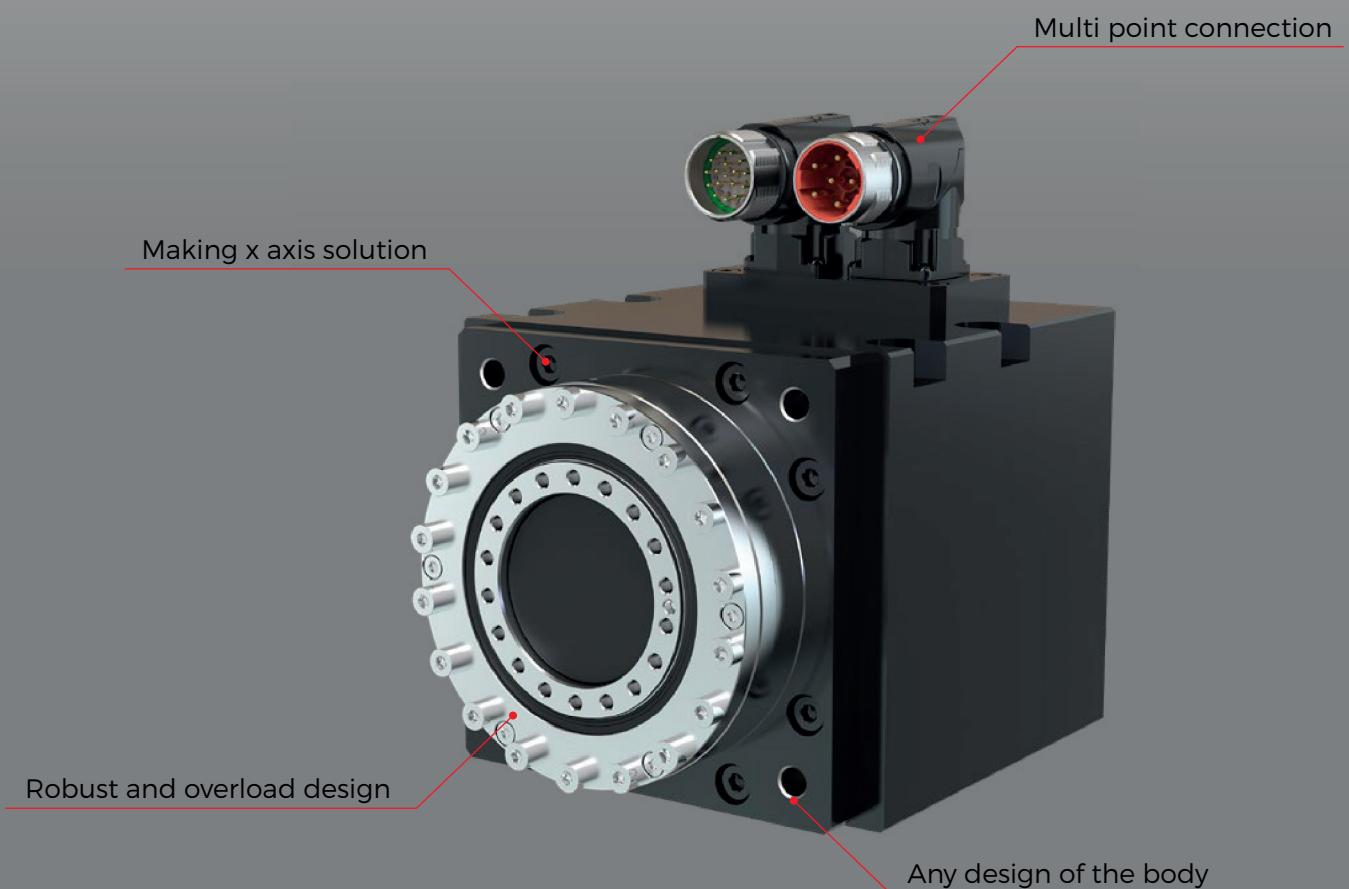




# DSM series



WHEN AIR IS BETTER THAN STEEL

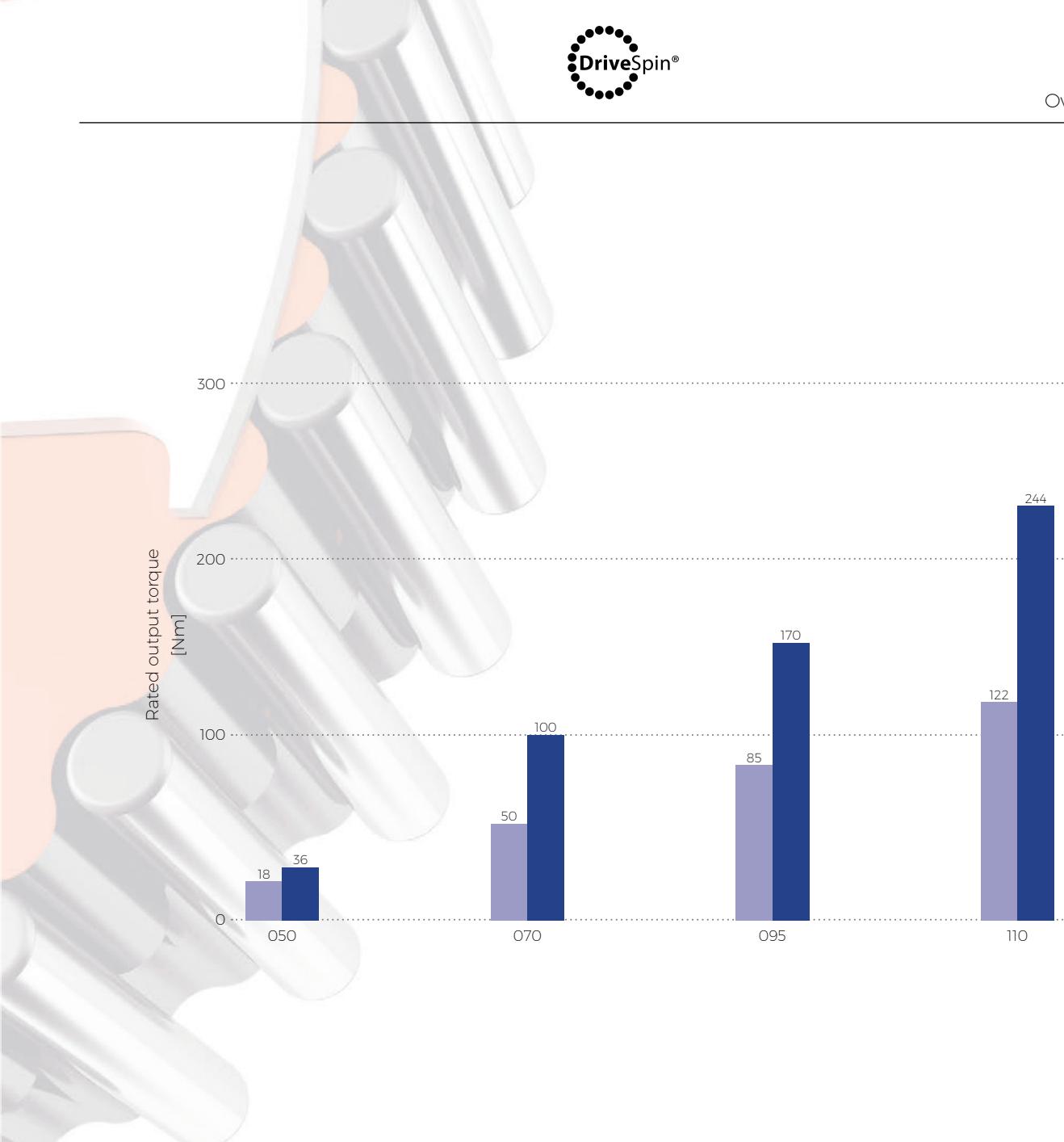
### 8.3 DSM series



#### Advantages

- **low lost motion**
- **low moment of inertia**
- **high reduction ratio**
- **high kinematic accuracy**
- **high moment overload capacity**
- **high capacity of the integrated radial-axial output bearings**
- **high dynamic performance**

The **DriveSpin® DSM** modular rotary positioning modules provide controlled rotary motion and transfer of torque with a high positioning accuracy and precision. The output flange of the module allows capturing both radial and axial forces. The modules feature a special design, which allows versatile connections, also without additional devices. Actuators can be combined in many ways using the modular system. The simple design integration ability and small dimensions allow creating kinematic assemblies from DSM modules for end effectors, but also for additional devices and positioners. The selection of a module size depends on the required load-carrying capacity and the number of degrees of freedom of the motion axis. The DSM Series is characterized by simple and quick assembly and reduces overall cost. Compact design ensures optimum mounting options and application possibilities, even in confined installation spaces. These actuators are used in applications with request of high torque density, precision and dynamics. Rated output torque is from 18 Nm to 122 Nm.



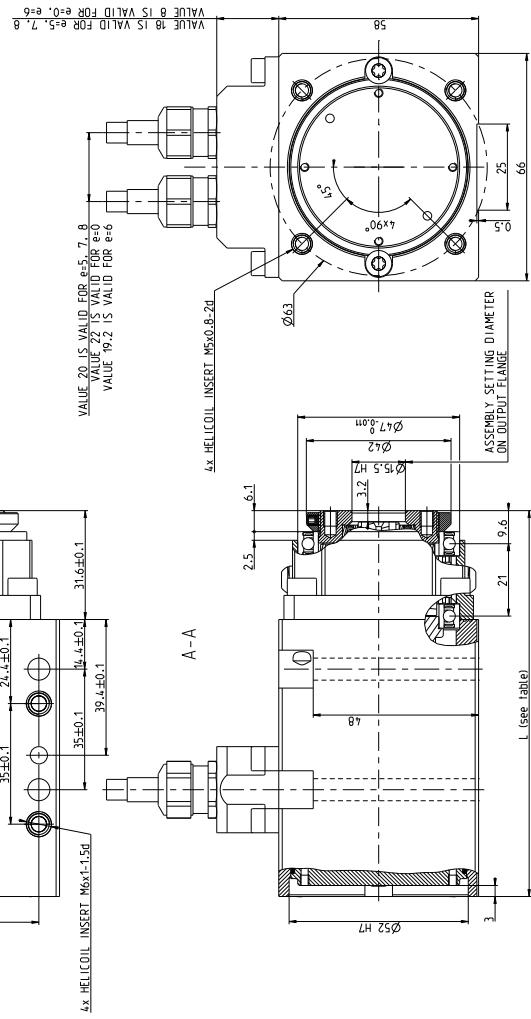
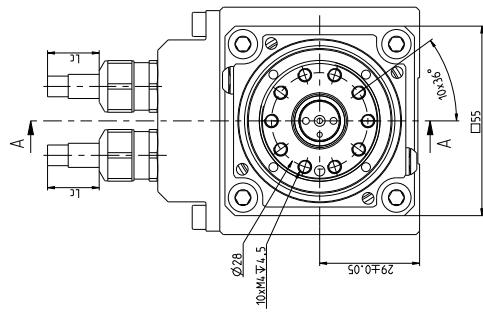
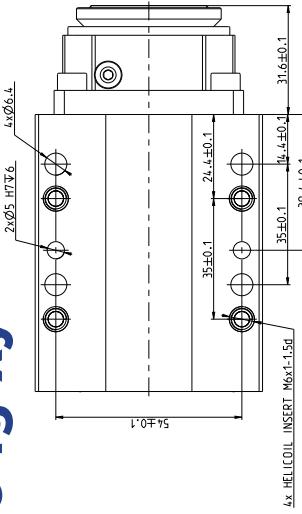
DSM

Tab. 8.3a: Rated output torque

Size		050	070	095	110
<b>Rated output torque</b>	$T_R$ [Nm]	18	50	85	122
<b>Acceleration/braking output torque</b>	$T_{acc}$ [Nm]	36	100	170	244

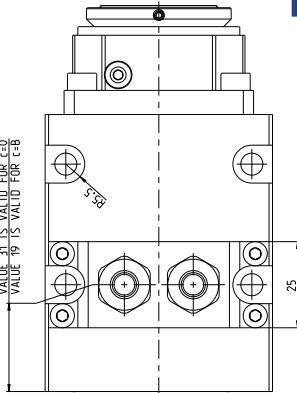
## DSM 050 - i - abcde-fg-xy

### DSM 050 - i - abcde-fg-xy



VALUE 16 IS VALID FOR e=6

L (see table)



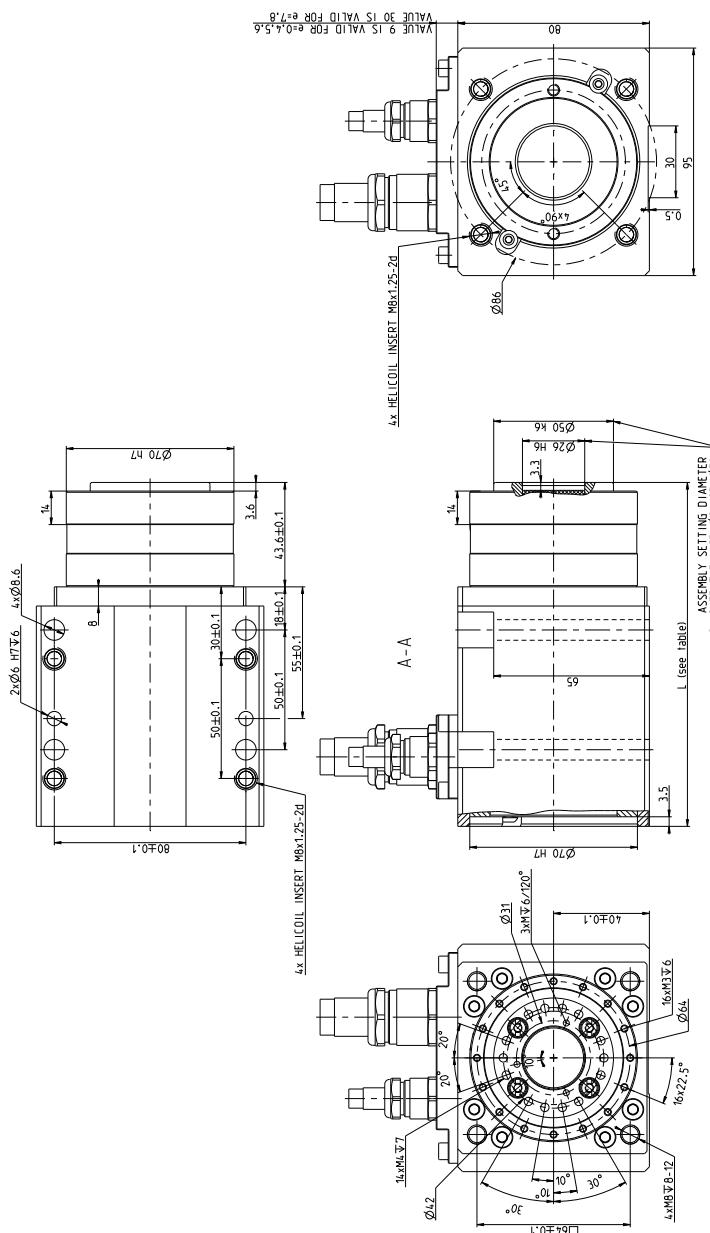
Size	Feedback type (d)	Without brake			With brake
		Dimension L ± 0.5 [mm]	Dimension L ± 0.5 [mm]	Weight m [kg] *	
DSM 050	OA	112	112	1.4	142
	OB, OC	112	112	1.4	142
	OD, OE	112	112	1.4	142
	OK, OL	119	119	1.4	152

## DSM 070 - i - abcde-fg-xy

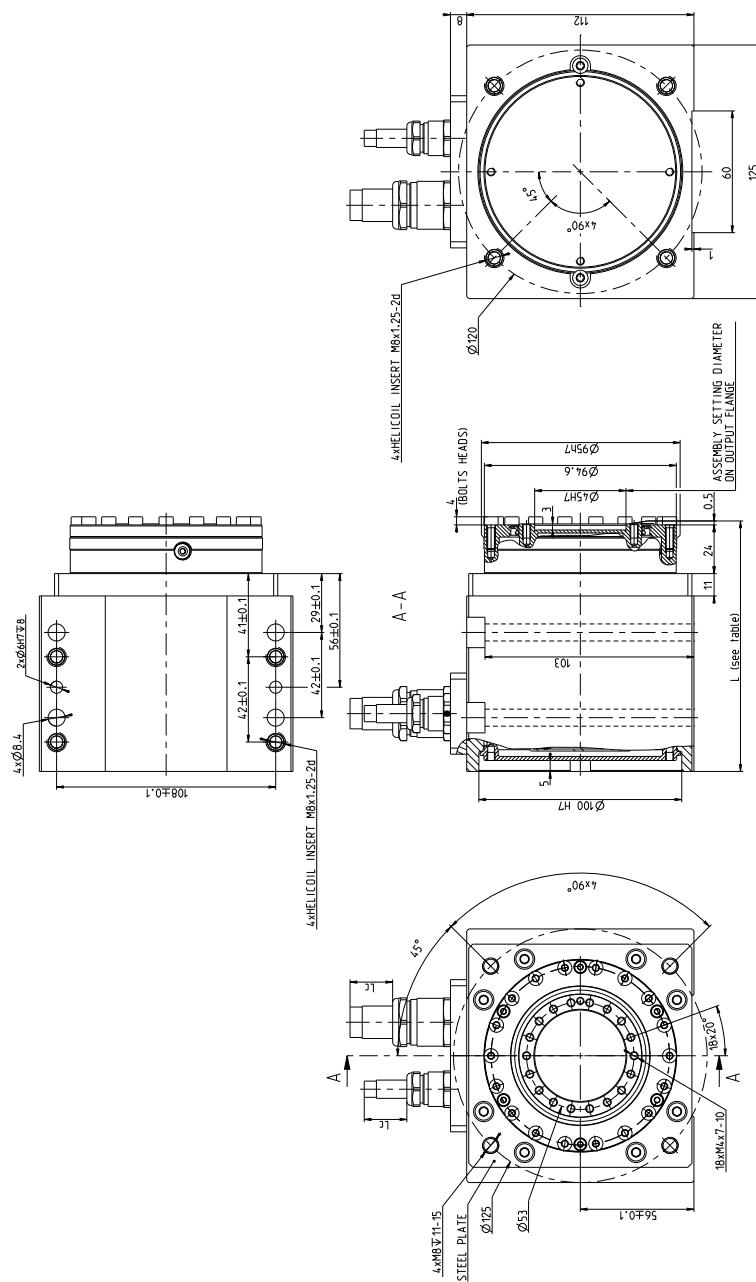
## DSM 070 - i - abcde-fg-xy



Projection



Size	Feedback type (d)	Without brake		With brake	
		Dimension L ± 0.5 [mm]	Weight m [kg]*	Dimension L ± 0.5 [mm]	Weight m [kg]*
DSM 070	OA	144	3.2	177	4.2
	OB,OC	144	3.2	177	4.8
	OD,OE	144	3.1	177	4.1
	OH	154	3.4	199	4.6

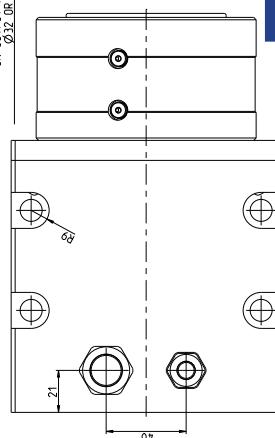
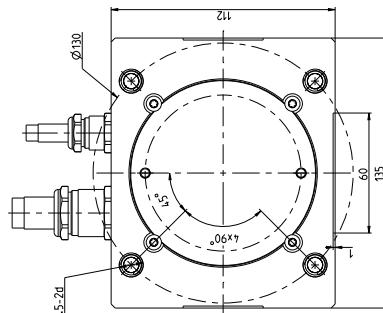
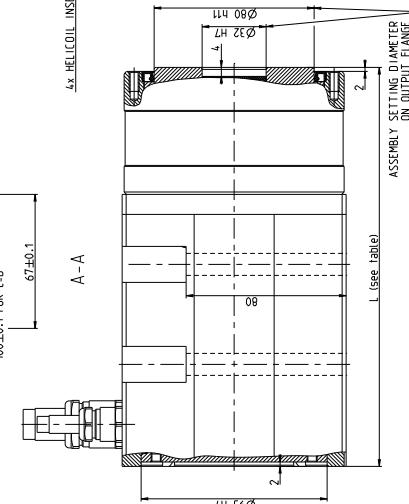
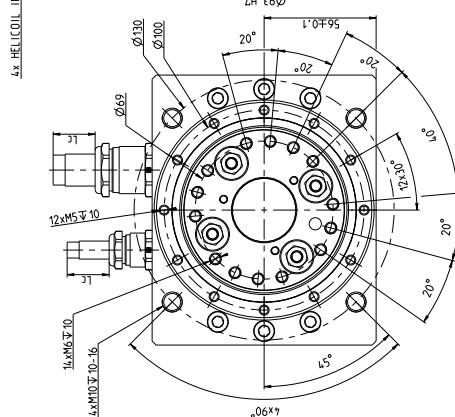
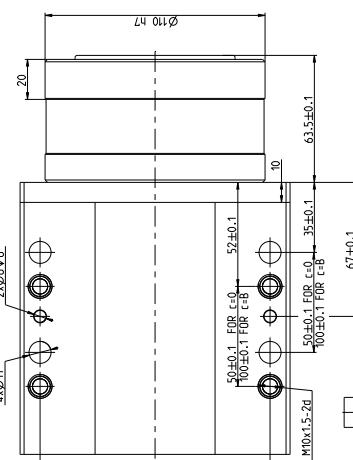
**DSM 095 - i - abcde-fg-xy**
**DSM 095 - i - abcde-fg-xy**


Size	Feedback type (d)	Without brake			With brake Weight m [kg] *
		Dimension L ± 0.5 [mm]	Weight m [kg] *	Dimension L ± 0.5 [mm]	
DSM 095	OA	122	5.9	145	6.5
	OB,OC	122	6.1	145	6.6
	OD,OE	122	6.0	145	6.7
	OG,OH,OF	142	6.6	165	7.3

# DSM 110 - i - abcde-fg-xy



Projection



Size	Feedback type (d)	Without brake		With brake	
		Dimension L ± 0.5 [mm]	Weight m [kg]*	Dimension L ± 0.5 [mm]	Weight m [kg]*
DSM 110	OA	200	10.5	252	12.4
	OB,OC	200	10.5	252	12.4
	OD,OE	200	10.6	252	12.5
	OH	200	10.6	252	12.5

Tab. 8.3b: DSM series technical data table

Reduction Gear parameters		Tolerance		DSM 050	
Reduction ratio	i			63	
Rated output torque	T <sub>R</sub> [Nm]			18	
Acceleration/braking output torque	T <sub>acc</sub> [Nm]			36	
Rated input speed	n <sub>r</sub> [rpm]			2 000	
Maximum allowable input speed <sup>9)</sup>	n <sub>max</sub> [rpm]			5 000	
Allowable moment <sup>2 3)</sup>	M <sub>cmax</sub> [Nm]			44	
Tilting stiffness <sup>1 6)</sup>	M <sub>t</sub> [Nm/arcmin]			4	
Torsional stiffness <sup>1 7)</sup>	k <sub>t</sub> [Nm/arcmin]			2.5	
Lost motion	LM [arcmin]			< 1.5	
Hysteresis	H [arcmin]			< 1.5	
Rated radial force <sup>2)</sup>	F <sub>rR</sub> [kN]			1.44 <sup>8)</sup>	
Maximum axial force <sup>2 4)</sup>	F <sub>a max</sub> [kN]			1.9	
Gear lubrication				Grease Castrol TRIBOL GR TT 1 PD	
Reduction gear limit temperature	[°C]			60 °C	
Standard ambient temperature range	[°C]			-10 °C to +40 °C	
Motor parameters					
DC BUS voltage	U <sub>dc</sub> [V <sub>dc</sub> ]	+/- 10%	24	320	560
Motor rated speed	n <sub>r</sub> [rpm]		3 500	3 500	3 500
Motor rated torque	M <sub>n</sub> [Nm]	+/- 10%	0.23	0.23	0.23
Motor rated current	I <sub>n</sub> [A <sub>rms</sub> ]		7.1	0.58	0.3
Motor stall torque	M <sub>o</sub> [Nm]	+/- 10%	0.24	0.24	0.24
Motor stall current	I <sub>o</sub> [A <sub>rms</sub> ]		7.4	0.6	0.3
Motor peak torque	M <sub>max</sub> [Nm]	+/- 10%	1	1	1
Motor peak current	I <sub>max</sub> [A]		30.8	2.5	1.25
Motor back-EMF constant	K <sub>E</sub> [V <sub>peak</sub> /krpm]	+/- 10%	2.7	36	67
Motor torque constant	K <sub>T</sub> [Nm/A <sub>rms</sub> ]	+/- 10%	0.032	0.4	0.8
Terminal resistance (L-L)	R <sub>2ph</sub> [Ω]	+/- 10%	0.2	36	122
Terminal inductance (L-L)	L <sub>2ph</sub> [mH]	+/- 20%	0.2	36	130
Number of poles	2p		6	6	6
Electromagnetic brake DC supply	[V <sub>dc</sub> ]			24, Special	
Electromagnetic brake torque at input	[Nm]			0.4	
Protection class				IP 64	
Motor Insulation class				F	
Paint				RAL 9005	
Motor number of phases				3	
Motor type of connection				Y(star-configuration)	

- 1) Mean statistical value
- 2) Load at output speed 32 rpm for size 050, other sizes at 15 rpm
- 3) Moment M<sub>c</sub> max at F<sub>a</sub>=0. If F<sub>a</sub>≠0 see Glossary
- 4) Axial force F<sub>a</sub> max for M<sub>c</sub>=0 (in case of size 050 also F<sub>r</sub>=0 condition has to be fulfilled). If M<sub>c</sub>≠0 see Glossary
- 5) 3 900 rpm for ratio 67 : 4 500 rpm for ratios 89, 119
- 6) The parameter depends on the version of high precision reduction gear.
- 7) The parameter depends on the version, ratio and lost motion of the high precision reduction gear.
- 8) For size 050 this is value of MAXIMUM RADIAL FORCE F<sub>r max</sub> for a<sub>2</sub>=0; F<sub>a</sub>=0 and at 32 rpm output speed. For a<sub>2</sub>>0; F<sub>a</sub>=0 at 32 rpm output speed F<sub>r max</sub>=0.044/(a<sub>2</sub>+0.0305) [kN]. a<sub>2</sub> represents the distance of the radial force centre from the front of the output flange in meters see Glossary.
- 9) Instantaneous speed peak that may occur within the working cycle. Note please the temperature on the gear case that should not exceed significantly 60°C
- 10) 4 500 rpm for ratio 73 ; 4 800 rpm for ratio 95

Tab. 8.3b: DSM series technical data table - continued

DSM 070			DSM 095			DSM 110		
57.75			73.95			67.89.119		
50			85			122		
100			170			244		
2 000			2 000			2 000		
5 000			4 500 / 4 800 <sup>10)</sup>			3 900 / 4 500 <sup>5)</sup>		
142			410			740		
35			120			150		
7			15			22		
< 1.5			< 1			< 1		
< 1.5			< 1			< 1		
2.8			3.5			9.3		
4.1			11.1			13.1		
Grease Castrol TRIBOL GR TT 1 PD			Grease Castrol TRIBOL GR TT 1 PD			Grease Castrol TRIBOL GR TT 1 PD		
60 °C			60 °C			60 °C		
-10 °C to +40 °C			-10 °C to +40 °C			-10 °C to +40 °C		
24	320	560	24	320	560	24	320	560
2 500	4 500	4 500	4 000	4 000	4 000	2 500	3 000	3 000
0.88	0.76	0.76	1.4	1.4	1.4	3.4	3.2	3.2
13	1.2	0.7	27	5.6	3.1	37	4.9	2.8
0.9	0.9	0.9	1.6	1.6	1.6	3.8	3.8	3.8
13.3	1.42	0.83	31	6.4	3.5	41	6	3
3	3	3	5.5	5.5	5.5	11	11	11
44.3	4.7	2.8	106.1	22	12.1	120	17	10
5.7	68.3	105.6	4.4	25	47	8	57	103
0.0677	0.63	1.09	0.052	0.25	0.46	0.09	0.65	1.14
0.13	17	40.5	0.052	1.2	4.36	0.027	1.4	4.5
0.25	34.4	87	0.11	2.84	8.71	0.15	7.4	24
10	10	10	10	10	10	10	10	10
24. Special			24. Special			24. Special		
4.5			2			4.5		
IP 64			IP 64			IP 64		
F			F			F		
RAL 9005			RAL 9005			RAL 9005		
3			3			3		
Y(star-configuration)			Y(star-configuration)			Y(star-configuration)		

**IMPORTANT NOTES:**

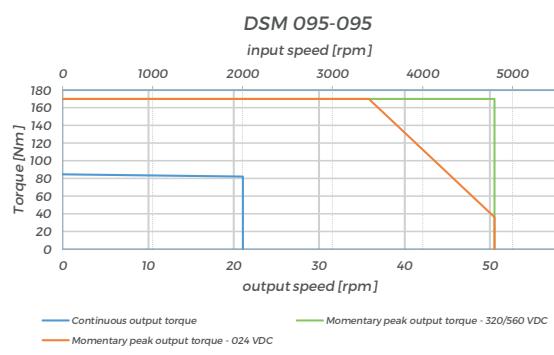
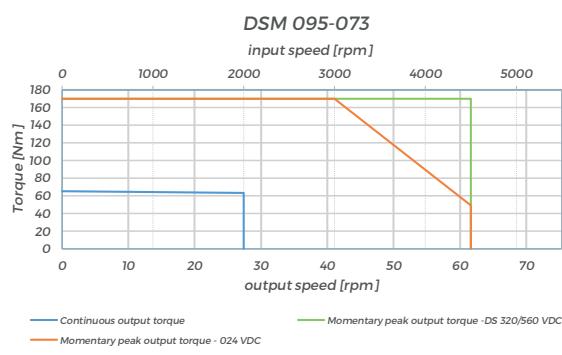
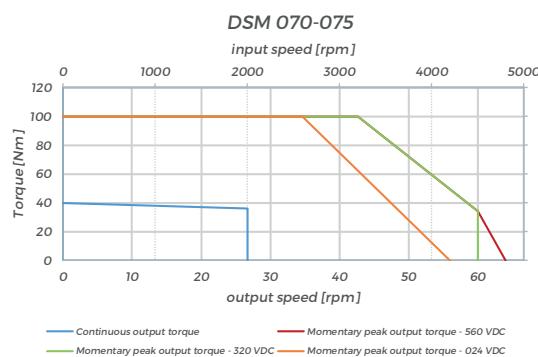
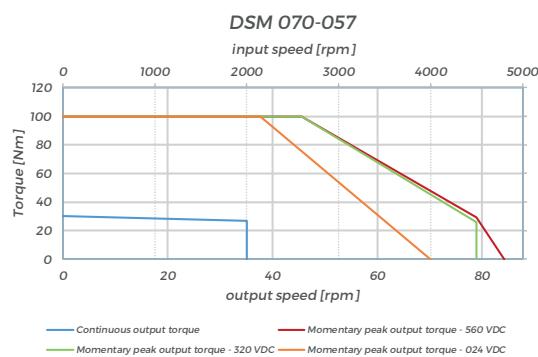
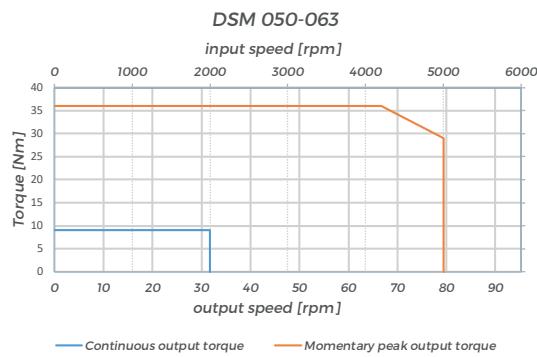
- Load values in the table are valid for the nominal life of  $L_{10} = 6\ 000$  hours. Service life for average torque  $T_a$  and average speed  $n_a$  other than  $T_R, n_R$  can be calculated. Please contact manufacturer with estimated duty cycle.
- High precision reduction gears are preferred for intermittent duty cycles (S3-S8); the output speed in applications is inverted-variable. The S1 continuous duty cycle needs to be consulted with manufacturer
- Please consult the maximum speed in duty cycle with the manufacturer
- The values in the table refer to the ambient temperature of 20°C to 25°C
- For ambient temperatures lower than -10°C pre-heating might be considered please consult manufacturer

Tab. 8.3c: Inertia at input (DSM actuator without brake)

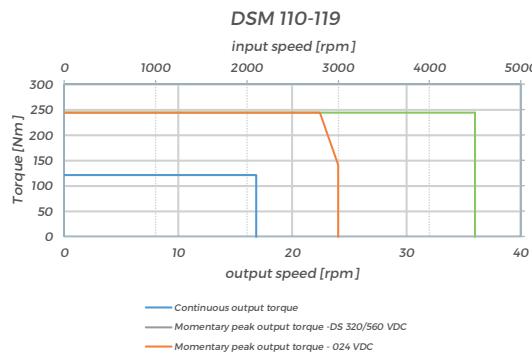
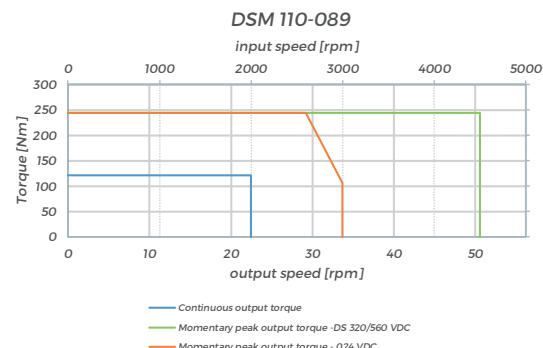
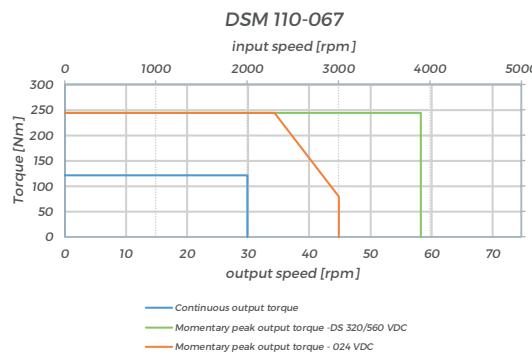
Feedback type (d)	$J_{w/o\ brake}$	DSM 050	DSM 070	DSM 095	DSM 110
OA	$10^{-4}\text{ kgm}^2$	0.062	0.420	1.657	1.825
OB	$10^{-4}\text{ kgm}^2$	0.061	0.487	1.646	1.814
OC	$10^{-4}\text{ kgm}^2$	0.061	0.487	1.646	1.814
OD	$10^{-4}\text{ kgm}^2$	0.037	0.416	1.640	1.830
OE	$10^{-4}\text{ kgm}^2$	0.037	0.416	1.640	1.830
OF	$10^{-4}\text{ kgm}^2$	-	-	1.661	-
OG	$10^{-4}\text{ kgm}^2$	-	-	1.661	-
OH	$10^{-4}\text{ kgm}^2$	-	0.416	1.661	1.830
OK	$10^{-4}\text{ kgm}^2$	0.060	-	-	-
OL	$10^{-4}\text{ kgm}^2$	0.060	-	-	-

Tab. 8.3d: Inertia at input (DSM actuator with brake)

Feedback type (d)	$J_{w/o\ brake}$	DSM 050	DSM 070	DSM 095	DSM 110
OA	$10^{-4}\text{ kgm}^2$	0.121	0.780	1.707	2.193
OB	$10^{-4}\text{ kgm}^2$	0.101	0.853	1.695	2.182
OC	$10^{-4}\text{ kgm}^2$	0.101	0.853	1.695	2.182
OD	$10^{-4}\text{ kgm}^2$	0.101	0.778	1.689	2.196
OE	$10^{-4}\text{ kgm}^2$	0.101	0.778	1.689	2.196
OF	$10^{-4}\text{ kgm}^2$	-	-	1.711	-
OG	$10^{-4}\text{ kgm}^2$	-	-	1.711	-
OH	$10^{-4}\text{ kgm}^2$	-	0.778	1.711	2.196
OK	$10^{-4}\text{ kgm}^2$	0.100	-	-	-
OL	$10^{-4}\text{ kgm}^2$	0.100	-	-	-



DSM



**Schweiz**



**Nozag AG**  
Barzloostrasse 1  
CH-8330 Pfäffikon/ZH

Telefon +41 44 805 17 17

Aussendienst Westschweiz  
Telefon +41 79 886 76 83

[www.nozag.ch](http://www.nozag.ch)  
[info@nozag.ch](mailto:info@nozag.ch)