

Motor attachment
Summary – System Program



What counts is success – We help you achieve it

Today clear competitive advantages and opportunities depend on flexibility, speed, innovation and continuous improvement. We understand that time has become one of the most significant competitive factors. In clearly defined markets, we offer advanced solutions that aim at optimum customer value. With internationally recognized quality, – our entire company is certified according to ISO 9001:2008 – high stock availability and maximum reliability, we aim at being a true partner for our customers. We are aware that a lasting partnership is built on mutual trust and understanding and will be further strengthened by absolute liability. Nozag employees commit themselves every day to win the confidence of clients and suppliers. Highly, above-average skilled employees and state-of-the art facilities are the basis for that.

In-house manufacturing is supported by high-performance logistics; this going along with simple, direct and to-the-point communication with our partners. We respect and comply with all pertinent laws, especially those that protect the environment and the health and safety of our workers.

Standard Program Standard parts, further processing



System Program Screwjack systems, standard gearboxes



Toothed components, electromechanical and pneumatic drives





System Program

- 1 Screw jacks
- 2 Bevel gearboxes
- 3 Connecting shafts
- 4 Linear drives
- 5 Gear, worm gear
- 6 Customer-specific construction group

Standard Program

- 7 Spur gears module 0.3 to 8
- 8 Bevel gears up to module 6
- 9 Worms and worm wheels
- 10 Standard racks
- 11 Trapezoid threaded screws, trapezoid threaded nuts
- 12 Chains and chain wheels
- 13 Couplings
- 14 Hardened precision steel shafts
- 15 Manufacturing according to drawing

Contents Catalog systems

Screw jack	
1. General/Basics	5
Modular system / Layout procedure / Practical applications / Application requirements / Base values / Design/Calculation	
2. Screw jacks, non-rotating	25
Application examples / Checklist / Sizes/System overview / Sizes/Models / Attachments / Length determination / Section drawing	
3. Screw jacks, rotating	61
Application examples / Checklist / Sizes/System overview / Sizes/Models / Attachments / Length determination / Section drawing	
4. Drive components	89
Connecting shafts / Pedestal bearings / Clamp coupling / Flexible couplings / Bevel gear LMA / Bevel gear RM	
5. Motor attachment	117
Principles / Motor adapter / Motor adapter / Motors power rating/output / Brake motors power rating/output / Rotary pulse encoders / Spring-loaded brake	
6. Maintenance	134
Assembly and Operating Manu	

Individual products and services	
7. Customer specific assemblies/gearboxes / Individual gear components / Hardened and ground precision shafts h6	149
8. General terms and conditions	157

We reserve the right on printing and dimension errors, as well as technical changes and improvements.

5. Motor attachment

Our screw jack kit makes it possible to install various motor sizes or types, including braking motors, matched according to the required lifting force, directly on the screw jack.

If there is not enough space for the brake on the motor side, the spring-loaded brake provides a solution. It is mounted on the free shaft end.

Table of Contents	Page
5.1 Principles	119
5.2 Motor adapter	121
5.3 Motors power rating/output	123
5.4 Brake motors power rating/output	127
5.5 Rotary pulse encoders	129
5.6 Spring-loaded brake	131

Properties/specifications

Rotational speeds

Three-phase motors have different rotational speeds, depending on the number of poles. Basically, we recommend that you should select our standard motor with 1400 min⁻¹ (4-pole). Other numbers of poles can be provided for upon request.

Rotational speed (50 Hz)	Number of poles
2800	2
1400	4
900	6
700	8

Braking motor

To reduce the overrun of the system to a minimum, we recommend using a braking motor. In the case of gearboxes with a ball screw drive or 2-thread spindles, a brake is absolutely necessary. Brake motors are supplied as standard with high torque DC brake (ATDC). Supply 230VAC. Other supply voltages can be provided upon request.

Operation with frequency converter FU

Especially in the case of large gearboxes and systems, we recommend the use of a frequency converter to achieve a uniform starting and braking ramp. This minimises the acceleration load and increases the operating life of the system. When using a frequency converter, it must be remembered that with prolonged operation below 25 Hz, an external fan is necessary. This is important to ensure sufficient cooling of the motor. If you operate a braking motor with a frequency converter, provide the brake with a separate control lead through the FU. This protects the system and increases the life.

Cooling

The motors are surface-cooled (IC411).

Upon request, motors with external ventilation can be supplied.

Condensation water holes

The motors size 63 to 132 have condensation water holes. Depending on the installation position, condensation water holes are made at the deepest point of the A- or B bearing plate. These are plugged with lens-head screws. Before initial operation and during operation, the condensation water holes should be opened regularly and the condensed water drained.

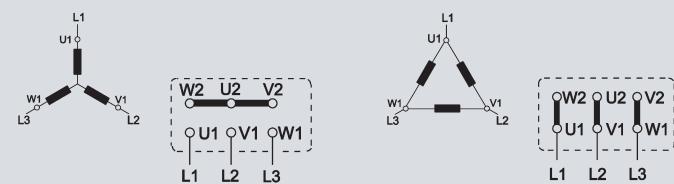
Thermosensors (TF)

Other common designations: Thermistor, thermistor thermo-sensor, PTC-thermistor. The resistance of the thermo-sensor jumps up suddenly upon reaching the rated actuation temperature (NAT) to almost ten times the value. The thermistor thermo-sensor fulfils its protective function only if there is a triggering device connected. The 4-pole motors of size 80 to 132 have thermosensors built in factory made.

Circuit diagramm for three-phase motors

The standard version of the motors have 6 stator terminals. By using exchangeable bridges, the stator winding can be connected in star (Y) or delta (Δ). For direct switching on, the operating circuit of the motor can be both star (Y), as well as delta (Δ). The star/delta starting process is not suitable for lifting jack systems, since the full torque is required right from the start.

Star and delta connection for motors with one rotational speed



RAL/NCS

Two component acryl paint are weather-resistant and resistant to petrol and cleaners. Motors with special paint (paints according to RAL shade no. or NCS shade no. available upon request)

(TROP) tropical protection /(FEU)-moisture protection

When using motors in extreme climatic conditions (tropics), we recommend the tropical protection version (encapsulated terminal box, winding with additional impregnation).

When using motors in a humid environment, we recommend the version with humidity protection insulation.

- Terminal boxes encapsulated

Housing and bearing shields

The standard housing of the motors size 56 to 112 is of aluminium pressure casting (size 132 of cast iron).

Bearing shields and flanges of the series 56 to 80 are made of aluminium pressure castings. Bearing shields and flanges of the series 90 to 132 are made of cast iron.

Universal version (stator housing)

The motors sizes 80 to 112 have unscrewable feet. The motor feet are fastened with two Allen screws each to the motor housing. The feet can also be screwed on to the sides of the motors, so that the terminal box positioning is possible to the left or the right. The motor housings already have suitable threaded holes for this purpose.

Universal version (terminal box cable glands)

Motors size 63 to 132 have unscrewable terminal boxes, which can be rotated through 45°. Therefore, the position of the metric cable glands can be freely selected. The terminal box is designed in protection class IP 55. Metric ISO fine threads according to EN 50262 are provided.

Rotor

The rotor is encapsulated in cast aluminium. The rotor and the shaft are dynamically balanced with half keys according to DIN ISO 8821.

Fan and fan hood

The fans for the motors size 56 to 132 are of plastic. The fan hood for all motors is made of sheet steel. Caution in case of damage to the fan hood; this could cause the fan to touch it.

Operating conditions of the motor

The technical values and data in this catalogue are based on the following fundamentals:

1. Continuous operation (S1)
2. Frequency 50 Hz
3. Rated voltage in the case of 3ph motors 400V. ±10%
1ph motors 230V. ±10%
4. Relative humidity up to 95%

Protection category

Unless otherwise specified, all motors are made with protection class IP 55 (IP...International Protection) (other protection classes can also be provided upon request).

Brake motors are delivered as safety class IP54, other safety classes on demand.

Insulation class

Unless otherwise specified, all motors are supplied with insulation class F. I.e. with an ambient temperature of 40°C, the permissible over-temperature in the winding is maximum 150°C. Insulation class H available upon request).

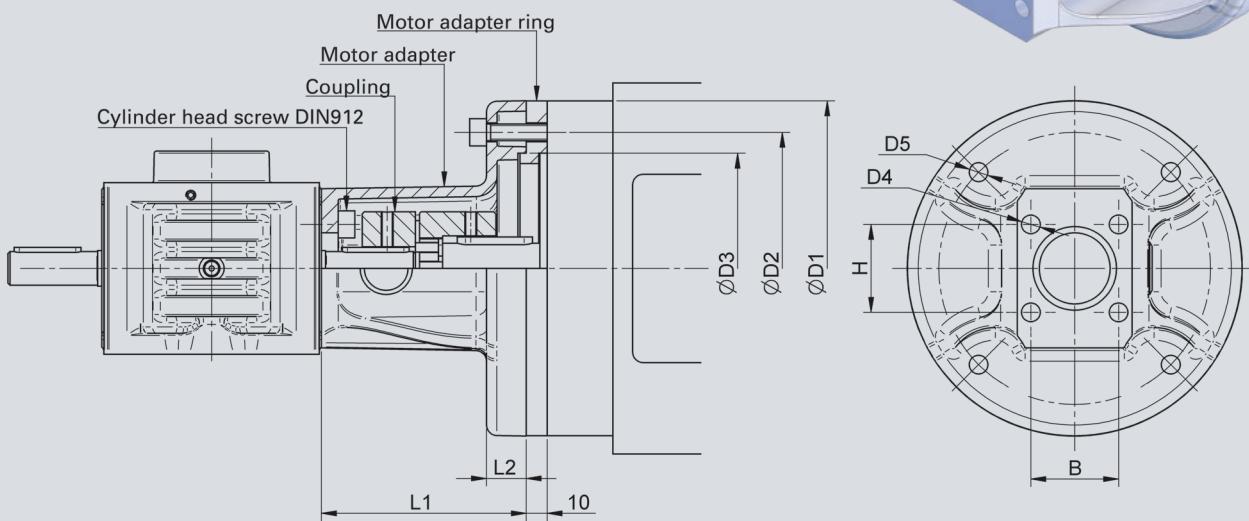
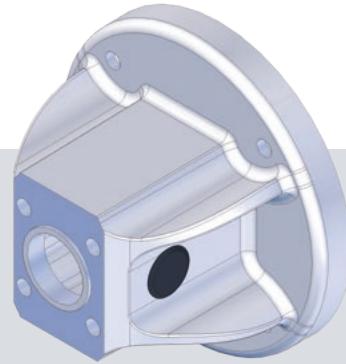
Options and special designs

The motors can also be built with the following options. Other special versions available upon request.

Abbreviation	Description of the special version
2WE	2 nd shaft end (shaft end according to IEC on both sides of the motor)
REDA	Rain roof (protection from foreign bodies falling into the fan)
TROP	Tropical protection version (use in extreme climatic conditions: Tropics)
FEU	Humidity protection version (terminal boxes encapsulated)
TF	Thermosensors (theristor, thermistor thermo-sensors, PTC-thermistor)
TW	Thermo-monitor (thermo-openers, Klixon, bimetallic opener)
FREMD	External fan (in use with frequency converter, low rotational speeds)
INKR	Incremental transmitter (rotational speed feedback)
OL	Without fan (cooling to be taken care of by the user)
SPWE	Special shaft (special shafts in accordance with customer request, drawing)
BLIN	Without terminal box (stator with dummy cover)
KABE	Terminal box with cable (cable from terminal box onwards according to customer request)
STIL	Standstill heating (prevents moisture in the interior of the motor)
RAL	Motor in special paint (paint according to RAL colour shade no.)
NCS	Motor in special paint (paint according to NCS colour shade no.)
KKU	Motor terminal boxes (terminal box position universal)
KKR	Motor terminal box (terminal box position to the right of the drive side)
KKL	Motor terminal box (terminal box position to the left of the drive side)
S	Motor with special voltage (special voltage according to customer request)
MOFU	Motor with frequency converter (frequency converter placed on motor)
SCH	Motor data plate (special motor data plate according to customer request)

Ordering example					
Size	Type 4-pole = 1400 min ⁻¹	Power kW	Construction	Brake on request	Special design
90	L	4	– 1.5 –	B3 – B –	—

Motor adapter



Apart from the requirement for a good, appealing design, simplicity and user-friendliness have played a significant role in this new development with a copyright design.

The motor adapter is made in such a way that simple fastening on the coupling used is possible.

Dimensions

	B	D1	D2	D3	D4	D5	H	L1	L2
NSE2-MOA120	28.3	120	100	80	5.5	6.6	28.3	59.0	5.5
NSE5-MOA140	32.5	140	115	95	6.6	9.0	32.5	65.0	12.0
NSE10-MOA160	35.4	160	130	110	9.0	9.0	35.4	70.5	17.0
NSE25-MOA160	42.0	160	130	110	9.0	9.0	42.0	98.0	19.0
NSE50-MOA200	50.0	200	165	130	11.0	11.0	70.0	110.5	23.5
NSE100-MOA200	46.0	200	165	130	13.0	11.0	96.0	142.0	25.0

System overview

Screw jack size	Motor				NSE			Motor adapter				Motor adapter ring	Coupling		Fixing	
	Motor size Motor flange	Power	Torque	Shaft diameter	Shaft diameter	Key width	Shaft length	Outside Ø	Inside Ø	Screw hole circle Ø	Length		Coupling	Insert*	Screw for gearbox	Screw for motor
2	56 B5	0.12	0.82	9	9	3	18	120	80	100	59.0	050	SOX	IS M5/10	IS M6/25 with 2 washer and nut	
	63 B14-1	0.25	1.70	11	11	4	22	120	80	100	59.0	050	SOX	IS M5/10	IS M6/15 with washer	
5	63 B5	0.25	1.70	11	11	4	22	140	95	115	65.0	050	SOX	IS M6/12	IS M8/35 with 2 washer and nut	
	71 B14-1	0.55	3.75	14	11	4	22	140	95	115	65.0	070	SOX	IS M6/12	IS M8/25 with washer	
10	71 B5	0.55	3.75	14	14	5	25	160	110	130	70.5	070	SOX	IS M8/14	IS M8/40 with 2 washer and nut	
	80 B14-1	1.10	10.4	19	14	5	25	160	110	130	70.5	yes	070	HYTREL	IS M8/14	IS M8/30 with washer
25	71 B5	0.55	3.75	14	16	5	43	160	110	130	98.0	095	SOX	IS M8/18	IS M8/40 with 2 washer and nut	
	80 B14-1	1.10	10.40	19	16	5	43	160	110	130	98.0	070	HYTREL	IS M8/18	IS M8/35 with washer	
	90 B14-1	2.20	15.20	24	16	5	43	160	110	130	98.0	yes	095	HYTREL	IS M8/18	IS M8/35 with washer
50	90 B5	2.20	15.20	24	20	6	45	200	130	165	110.5	095	HYTREL	IS M10/22	IS M10/50 with 2 washer and nut	
	100 B14-1	4.00	27.00	28	20	6	45	200	130	165	110.5	yes	095	HYTREL	IS M10/22	IS M10/40 with washer
	112 B14-1	5.50	37.00	28	20	6	45	200	130	165	110.5	yes	100	SOX	IS M10/22	IS M10/40 with washer
100	90 B5	2.20	15.20	24	25	8	57	200	130	165	142.0	100	SOX	IS M12/30	IS M10/50 with 2 washer and nut	
	100 B14-1	4.00	27.00	28	25	8	57	200	130	165	142.0	095	HYTREL	IS M12/30	IS M10/40 with washer	
	112 B14-1	5.50	37.00	28	25	8	57	200	130	165	142.0	100	SOX	IS M12/30	IS M10/40 with washer	

IS = Hexagon socket screw DIN912

* 92 = Urethan insert 92 Shore A (with/yellow)/98 = Urethan insert 98 Shore A (red)



Flexible couplings on Chapter 4

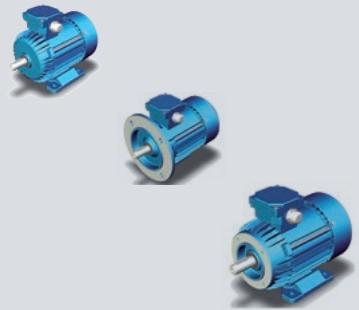
5.3 Motors power rating/output

Motor attachment

Motor output

motor output and revolutions (r.p.m) for IEC sizes

Motor by IEC	Type	1400 min ⁻¹		IE Norm	900 min ⁻¹		IE Norm	700 min ⁻¹		IE Norm
		kW	kW		kW	kW		kW	kW	
56	A	0.06	1							
56	B	0.09	1							
56	XC	0.12	1							
63	A	0.12	1		0.09	1				
63	B	0.18	1		0.12	1				
63	XC	0.25	1		0.15	1				
71	A	0.25	1		0.18	1		0.09	1	
71	B	0.37	1		0.25	1		0.12	1	
71	XC	0.55	1		0.37	1				
80	A	0.55	1		0.37	1		0.18	1	
80	B	0.75	2		0.55	1		0.25	1	
80	XC	1.10	2		0.75	2				
90	S	1.10	2		0.75	2		0.37	1	
90	L	1.50	2		1.10	2		0.55	1	
100	LA	2.20	2					0.75	1	
100	LB	3.00	2		1.50	2		1.10	1	
112	M	4.00	2		2.20	2		1.50	1	
112	MA	5.50	2		3.00	2				
132	S	5.50	2		3.00	2		2.20	1	
132	M	7.50	3		4.00	2		3.00	1	
132	MA	9.20	2		5.50	2				

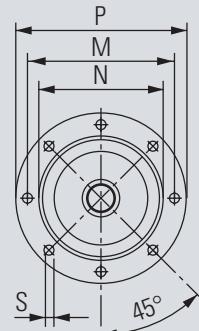


Motor flange

Dimensions of flange models

IEC Motor	B5				B14 -1				B14 -2					
	P	M	N	Sø	Z	P	M	N	S	Z	P	M	N	S
56	120	100	80	6.6	4	105	85	70	M6	4	80	65	50	M5
63	140	115	95	9.0	8	120	100	80	M6	8	90	75	60	M5
71	160	130	110	9.0	8	140	115	95	M8	8	105	85	70	M6
80	200	165	130	11	8	160	130	110	M8	8	120	100	80	M6
90	200	165	130	11	8	160	130	110	M8	8	140	115	95	M8
100	250	215	180	14	8	200	165	130	M10	8	160	130	110	M8
112	250	215	180	14	8	200	165	130	M10	8	160	130	110	M8
132	300	265	230	14	8	250	215	180	M12	8	200	165	130	M10

Flange 63-132

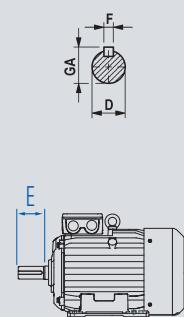


Motor shaft

Dimensions of shaft model

IEC Motor	Poles		D ømm	E mm	GA mm	F mm
	IEC	Motor				
56	2-6		9	20	10.2	3
63	2-8		11	23	12.5	4
71	2-8		14	30	16.0	5
80	2-8		19	40	21.5	6
90	2-8		24	50	27.0	8
100	2-8		28	60	31.0	8
112	2-8		28	60	31.0	8
132	2-8		38	80	41.0	10

Shaft 56-132



5.3 Motors power rating/output

Motor attachment

Motors

IEC	Type	Poles	Power rating (kW)	Model	Brake	Options
56	A	2 2800 min ⁻¹	0.06	B3 Foot	B	2WE 2 nd shaft end
63	B	4 1400 min ⁻¹	11.00	B5 Flange	—	REDA rain roof
71	X	6 900 min ⁻¹		B14-1 Flange		TROP Tropical protection (IP54)
80	B	8 750 min ⁻¹		B14-2 Flange		FEU Humidity protection
90	L					TF Thermosensor
100	LB					TW Thermomonitor
112	M					FREM External fan
132	S					INKR Incremental transmitter
	M					OL without fan
	MA					SPWE Special shaft
						BLIN without terminal box
						KABE Terminal box with cable
						STIL Standstill heating
						RAL motor with special paint
						NCS motor with special paint
						KKU Motor terminal box universal
						KKR Motor terminal box right
						KKL Motor terminal box left
						S Motor with special voltage
						MOFU Motor with frequency converter
						SCH motor data plate

5.3 Motors power rating/output

Motor attachment

Three-phase motors 1400 min⁻¹

3Ph motor IEC 60034.30 400 Volt +/- 10 % IP55 Isol.Cl. F Serv. S1

IEC	Type	kW	min ⁻¹	Nm	V	I _{Na}	W	kg	Ø WE	L We	K.K	IE Norm
56	A 4	0.06	1400	0.41	230/400	0.25	55.0	2.6	9	20	o	1
56	B 4	0.09	1400	0.61	230/400	0.40	61.0	2.8	9	20	o	1
56	XC 4	0.12	1400	0.82	230/400	0.50	59.0	4.0	9	20	o	1
63	A 4	0.12	1380	0.83	230/400	0.45	60.0	3.5	11	23	o	1
63	B 4	0.18	1380	1.25	230/400	0.65	65.0	4.2	11	23	o	1
63	XC 4	0.25	1400	1.70	230/400	0.77	69.0	5.0	11	23	o	1
71	A 4	0.25	1380	1.73	230/400	0.85	66.0	4.8	14	30	o	1
71	B 4	0.37	1370	2.59	230/400	1.30	68.0	5.9	14	30	o	1
71	XC 4	0.55	1400	3.86	230/400	1.54	70.0	7.2	14	30	o	1
80	A 4	0.55	1400	3.75	230/400	1.70	72.0	7.5	19	40	u	1
80	B 4	0.75	1400	5.12	230/400	2.20	80.0	9.6	19	40	u	2
80	XC 4	1.10	1380	7.61	230/400	3.00	81.4	11.5	19	40	u	2
90	S 4	1.10	1425	7.62	230/400	2.60	81.4	16.3	24	50	u	2
90	L 4	1.50	1425	10.10	230/400	3.40	82.8	18.0	24	50	u	2
100	LA 4	2.20	1440	14.60	230/400	4.50	84.7	25.5	28	60	u	2
100	LB 4	3.00	1445	19.80	400/690	6.80	85.5	27.5	28	60	u	2
112	M 4	4.00	1550	26.30	400/690	8.40	87.0	35.5	28	60	u	2
112	MA 4	5.50	1440	36.50	400/690	11.50	87.7	39.0	28	60	u	2
132	S 4	5.50	1460	36.00	400/690	11.30	88.0	69.0	38	80	o	2
132	M 4	7.50	1460	49.10	400/690	15.30	88.7	73.5	38	80	o	3

Approximate values, exact data sheets on request.

Three-phase motors 900 min⁻¹

3Ph motor IEC 60034.30 400 Volt +/- 10 % IP55 Isol.Cl. F Serv. S1

IEC	Type	kW	min ⁻¹	Nm	V	I _{Na}	W	kg	Ø WE	L We	K.K	IE Norm
63	B 6	0.12	880	1.30	230/400	0.65	50.0	4.2	11	23	o	1
63	XC 6	0.15	870	1.65	230/400	1.00	45.0	5.1	11	23	o	1
71	A 6	0.18	890	1.93	230/400	0.75	57.0	4.8	14	30	o	1
71	B 6	0.25	860	2.78	230/400	1.00	55.0	5.8	14	30	o	1
71	XC 6	0.37	880	4.02	230/400	1.35	60.0	7.3	14	30	o	1
80	A 6	0.37	910	3.88	230/400	1.40	64.0	7.4	19	40	u	1
80	B 6	0.55	900	5.84	230/400	1.80	67.0	8.6	19	40	u	1
80	XC 6	0.75	920	7.80	230/400	2.25	75.9	7.3	19	40	u	2
90	S 6	0.75	925	7.70	230/400	2.00	75.9	16.5	24	50	u	2
90	L 6	1.10	910	11.50	230/400	2.90	78.1	18.2	24	50	u	2
100	L 6	1.50	950	15.10	230/400	3.70	80.3	22.0	28	60	u	2
112	M 6	2.20	955	22.00	230/400	5.10	82.3	32.0	28	60	u	2
132	S 6	3.00	945	30.30	400/690	6.60	83.3	50.0	38	80	o	2
132	MA 6	4.00	950	40.20	400/690	8.40	84.6	62.0	38	80	o	2
132	MB 6	5.50	950	55.30	400/690	11.70	86.0	72.0	38	80	o	2

Approximate values, exact data sheets on request.

- Nm Nominal torque in Nm
- V Voltage
- I_{Na} Nominal current in A
- W Efficiency in %
- kg Weight on bases B3 (foot version)
- Ø WE IEC-Shaft diameter
- L WE IEC-Shaft length
- K.K Terminal box o > above
Terminal box u > universal (above, right, left)

5.3 Motors power rating/output

Motor attachment

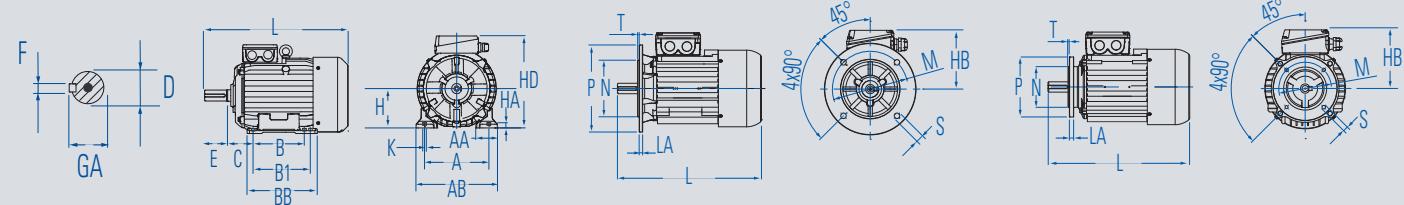
Three-phase motors 700 min⁻¹

3Ph motor IEC 60034-30 400 Volt +/- 10 % IP55 Isol.Cl. F Serv. S1

IEC	Type	kW	min ⁻¹	Nm	V	I _{na}	W	kg	ø WE	L We	K.K	IE Norm
63	B 8	0.06	670	0.85	230/400	0.45	38.0	4.2	11	23	0	1
71	A 8	0.09	680	1.26	230/400	0.75	35.0	4.9	14	30	0	1
71	B 8	0.12	670	1.71	230/400	0.70	47.0	5.8	14	30	0	1
71	XC 8	0.18	680	2.53	230/400	1.40	45.0	7.3	14	30	0	1
80	A 8	0.18	680	2.53	230/400	0.90	53.0	7.5	19	40	u	1
80	B 8	0.25	680	3.51	230/400	1.20	57.0	8.9	19	40	u	1
80	XC 8	0.37	680	5.20	230/400	1.70	58.0	11.0	19	40	u	1
90	S 8	0.37	695	5.10	230/400	1.40	63.4	13.4	24	50	u	1
90	L 8	0.55	675	7.80	230/400	1.90	65.0	15.3	24	50	u	1
100	LA 8	0.75	710	10.10	230/400	2.30	71.1	23.6	28	60	u	1
100	LB 8	1.10	705	14.90	230/400	3.40	72.2	26.3	28	60	u	1
112	M 8	1.50	720	19.90	230/400	4.00	76.8	31.0	28	60	u	1
132	S 8	2.20	710	29.60	230/400	5.50	78.0	53.0	38	80	o	1
132	M 8	3.00	710	40.40	230/400	7.30	80.0	65.0	38	80	o	1

Approximate values, exact data sheets on request.

Dimensions of 3-phase motor from sizes 56 -132



IEC Type	Pols	Base*						Housing*			Shaft			Flange B5					Flange B14-1					Flange B14-2								
		H	B	A	HA	BB	AB	K	AA	L	HD	C	D	E	GA	F	LA	P	N	M	T	S	P	N	M	T	S	P	N	M	T	S
56 A	2-4	56	71	90	7	92	110	8	30	188	154	36	9	20	10.2	3	8	120	80	100	3.0	7	105	70	85	2.5	M6	80	65	50	2.5	M5
56 B	2-4	56	71	90	7	92	110	8	30	196	154	36	9	20	10.2	3	8	120	80	100	3.0	7	105	70	85	2.5	M6	80	65	50	2.5	M5
63 A	2-8	63	80	100	8	106	124	7	36	201	165	40	11	23	12.5	4	9	140	95	115	3.0	10	120	80	100	3.0	M6	90	60	75	2.5	M5
63 B	2-8	63	80	100	8	106	124	7	36	213	165	40	11	23	12.5	4	9	140	95	115	3.0	10	120	80	100	3.0	M6	90	60	75	2.5	M5
63 XC	2-8	63	80	100	8	106	124	7	36	228	165	40	11	23	12.5	4	9	140	95	115	3.0	10	120	80	100	3.0	M6	90	60	75	2.5	M5
71 A	2-8	71	90	112	8	116	142	7	45	223	182	45	14	30	16.0	5	9	160	110	130	3.5	10	140	95	115	3.5	M8	105	70	85	3.0	M6
71 B	2-8	71	90	112	8	116	142	7	45	245	182	45	14	30	16.0	5	9	160	110	130	3.5	10	140	95	115	3.5	M8	105	70	85	3.0	M6
71 XC	2-8	71	90	112	8	116	142	7	45	266	200	45	14	30	16.0	5	9	160	110	130	3.5	10	140	95	115	3.5	M8	105	70	85	3.0	M6
80 A	2-8	80	100	125	9	130	160	10	55	266	200	50	19	40	21.5	6	10	200	130	165	3.5	12	160	110	130	3.5	M8	120	80	100	3.0	M6
80 B	2-8	80	100	125	9	130	160	10	55	278	200	50	19	40	21.5	6	10	200	130	165	3.5	12	160	110	130	3.5	M8	120	80	100	3.0	M6
80 XC	2-6	80	100	125	9	130	160	10	55	306	200	50	19	40	21.5	6	10	200	130	165	3.5	12	160	110	130	3.5	M8	120	80	100	3.0	M6
90 S	2-8	90	100	140	12	153	170	10	41	331	228	56	24	50	27.0	8	10	200	130	165	3.5	12	160	110	130	3.5	M8	140	95	115	3.0	M8
90 L	2-8	90	125	140	12	153	170	10	41	356	228	56	24	50	27.0	8	10	200	130	165	3.5	12	160	110	130	3.5	M8	140	95	115	3.0	M8
100 LA	2-8	100	140	160	14	174	197	12	44	440	240	63	28	60	31.0	8	11	250	180	215	4.0	15	200	130	165	3.5	M10	160	110	130	3.5	M8
100 LB	2-8	100	140	160	14	174	197	12	44	440	240	63	28	60	31.0	8	11	250	180	215	4.0	15	200	130	165	3.5	M10	160	110	130	3.5	M8
112 M	2-8	112	140	190	14	174	230	12	49	416	276	70	28	60	31.0	8	12	250	180	215	4.0	15	200	130	165	3.5	M10	160	110	130	3.5	M8
112 MA	2-6	112	140	190	14	174	230	12	49	466	276	70	28	60	31.0	8	12	250	180	215	4.0	15	200	130	165	3.5	M10	160	110	130	3.5	M8
132 S	2-8	132	140	216	16	220	274	12	62	499	310	89	38	80	41.0	10	12	300	230	265	4.0	15	250	180	215	4.0	M12	200	130	165	3.5	M10
132 M	2-8	132	178	216	16	220	274	12	62	531	310	89	38	80	41.0	10	12	300	230	265	4.0	15	250	180	215	4.0	M12	200	130	165	3.5	M10
132 MA	2-4	132	178	216	16	220	274	12	62	531	310	89	38	80	41.0	10	12	300	230	265	4.0	15	250	180	215	4.0	M12	200	130	165	3.5	M10

* Subject to change without notice, exact dimension sheets on request.

5.4 Brake motors power rating/output

Motor attachment

Three-phase motors 1400 min⁻¹

3Ph Brake motor IEC 60034.30 400 Volt +/- 10 % IP54 Isol.Cl. F Serv. S1

IEC	Type	kW	min ⁻¹	Nm	V	I _{na}	W	kg	Ø WE	L We	DC brake Nm
63	A 4	0.12	1355	0.92	230/400	0.40	64.7	8.5	11	23	4.5
63	B 4	0.18	1393	1.23	230/400	0.56	68.2	8.7	11	23	4.5
63	C 4	0.25	1380	1.73	230/400	0.72	71.0	9.7	11	23	4.5
71	A 4	0.25	1400	1.71	230/400	0.69	72.7	11.0	14	30	8.0
71	B 4	0.37	1366	2.59	230/400	1.04	71.5	11.3	14	30	8.0
71	C 4	0.55	1400	3.75	230/400	1.47	74.9	12.3	14	30	8.0
80	A 4	0.55	1391	3.78	230/400	1.49	75.0	15.5	19	40	12.5
80	B 4	0.75	1394	5.14	230/400	1.99	79.6	16.5	19	40	12.5
80	C 4	1.10	1390	7.56	230/400	2.85	81.5	18.0	19	40	12.5
90	S 4	1.10	1378	7.62	230/400	2.50	81.4	19.0	24	50	20.0
90	L 4	1.50	1413	10.10	230/400	3.54	82.9	20.0	24	50	20.0
90	LB 4	1.90	1415	12.80	230/400	4.47	84.3	22.0	24	50	20.0
100	LA 4	2.20	1435	14.60	230/400	4.80	84.4	30.0	28	60	38.0
100	LB 4	3.00	1407	20.30	400/690	6.39	85.5	32.0	28	60	38.0
112	M 4	4.00	1415	27.00	400/690	7.75	86.6	38.5	28	60	55.0
112	MB 4	5.00	1445	33.00	400/690	10.20	87.7	45.0	28	60	55.0
132	S 4	5.50	1446	36.30	400/690	10.70	87.8	57.0	38	80	90.0
132	M 4	7.50	1450	49.40	400/690	14.30	88.8	59.0	38	80	90.0

Approximate values, exact data sheets on request.

Three-phase motors 900 min⁻¹

3Ph Brake motor IEC 60034.30 400 Volt +/- 10 % IP54 Isol.Cl. F Serv. S1

IEC	Type	kW	min ⁻¹	Nm	V	I _{na}	W	kg	Ø WE	L We	DC brake Nm
71	A 6	0.18	921	1.87	230/400	0.66	62.7	11.0	14	30	8.0
71	B 6	0.25	910	2.62	230/400	0.87	64.0	11.3	14	30	8.0
80	A 6	0.37	928	3.81	230/400	1.20	67.3	15.5	19	40	12.5
80	B 6	0.55	917	5.73	230/400	1.71	70.5	16.5	19	40	12.5
90	S 6	0.75	915	7.83	230/400	2.01	76.0	19.0	24	50	20.0
90	L 6	1.10	915	11.48	230/400	2.74	78.3	20.0	24	50	20.0
100	LA 6	1.50	944	15.17	230/400	3.91	79.9	30.0	28	60	38.0
112	M 6	2.20	951	22.09	230/400	5.45	81.9	35.0	28	60	55.0
132	S 6	3.00	969	29.57	230/400	6.95	84.5	40.0	38	80	90.0
132	M 6	4.00	969	39.42	400/690	8.85	84.7	57.0	38	80	90.0
132	MB 6	5.50	969	54.37	400/690	12.38	87.0	67.0	38	80	90.0

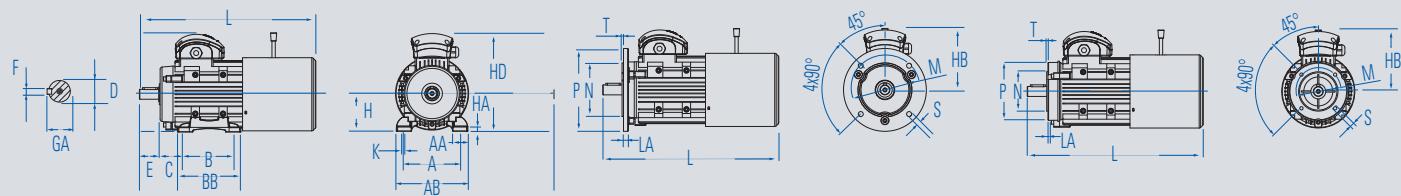
Approximate values, exact data sheets on request.

- Nm Nominal torque in Nm
- V Voltage
- I_{na} Nominal current in A
- W Efficiency in %
- kg Weight on bases B3 (foot version)
- Ø WE IEC-Shaft diameter
- L WE IEC-Shaft length

5.4 Brake motors power rating/output

Motor attachment

Dimensions of 3-phase motor from sizes 63-132

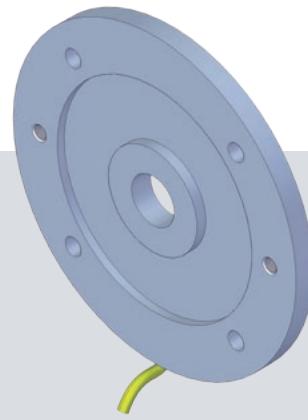
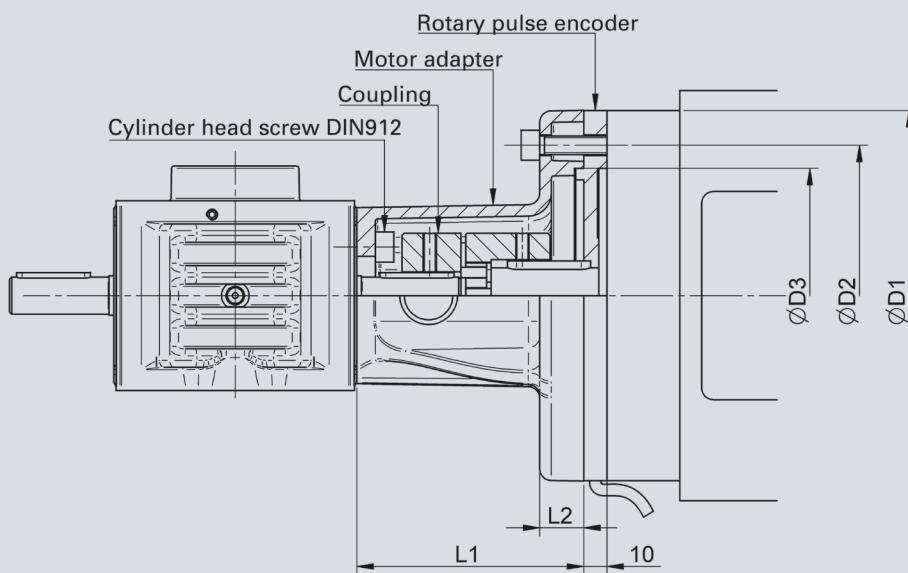


IEC Type	Pols	Base*					Housing*			Shaft			Flange B5					Flange B14-1					Flange B14-2						
		H	B	A	AB	K	L	HD	C	D	E	GA	F	LA	P	N	M	T	S	P	N	M	T	S	P	N	M	T	S
63 A	2-6	63	80	100	123	7	261	179	40	11	23	12.5	4	9	140	95	115	3.0	10	120	80	100	3.0	M6	90	60	75	2.5	M5
63 B	2-6	63	80	100	123	7	261	179	40	11	23	12.5	4	9	140	95	115	3.0	10	120	80	100	3.0	M6	90	60	75	2.5	M5
71 A	2-6	71	90	112	138	7	295	195	45	14	30	16.0	5	9	160	110	130	3.5	10	140	95	115	3.5	M8	105	70	85	3.0	M6
71 B	2-6	71	90	112	138	7	295	195	45	14	30	16.0	5	9	160	110	130	3.5	10	140	95	115	3.5	M8	105	70	85	3.0	M6
71 C	2-6	71	90	112	138	7	295	195	45	14	30	16.0	5	9	160	110	130	3.5	10	140	95	115	3.5	M8	105	70	85	3.0	M6
80 A	2-6	80	100	125	157	10	340	219	50	19	40	21.5	6	10	200	130	165	3.5	10	160	110	130	3.5	M8	120	80	100	3.0	M6
80 B	2-6	80	100	125	157	10	340	219	50	19	40	21.5	6	10	200	130	165	3.5	10	160	110	130	3.5	M8	120	80	100	3.0	M6
80 C	2-6	80	100	125	157	10	340	219	50	19	40	21.5	6	10	200	130	165	3.5	10	160	110	130	3.5	M8	120	80	100	3.0	M6
90 S	2-6	90	100	140	173	10	385	236	56	24	50	27.0	8	10	200	130	165	3.5	12	160	110	130	3.5	M8	140	95	115	3.0	M8
90 L	2-6	90	125	140	173	10	410	236	56	24	50	27.0	8	10	200	130	165	3.5	12	160	110	130	3.5	M8	140	95	115	3.0	M8
90 LB	2-6	90	125	140	173	10	410	236	56	24	50	27.0	8	10	200	130	165	3.5	12	160	110	130	3.5	M8	140	95	115	3.0	M8
100 LA	2-6	100	140	160	196	12	450	261	63	28	60	31.0	8	11	250	180	215	4.0	15	200	130	165	3.5	M10	160	110	130	3.5	M8
100 LB	2-6	100	140	160	196	12	450	261	63	28	60	31.0	8	11	250	180	215	4.0	15	200	130	165	3.5	M10	160	110	130	3.5	M8
112 M	2-6	100	140	190	227	12	475	289	70	28	60	31.0	8	12	250	180	215	4.0	15	200	130	165	3.5	M10	160	110	130	3.5	M8
112 MB	2-6	112	140	190	227	12	475	289	70	28	60	31.0	8	12	250	180	215	4.0	15	200	130	165	3.5	M10	160	110	130	3.5	M8
132 S	2-6	132	140	216	262	12	550	327	89	38	80	41.0	10	12	300	230	265	4.0	15	250	180	215	4.0	M12	200	130	165	3.5	M10
132 M	2-6	132	178	216	262	12	550	327	89	38	80	41.0	10	12	300	230	265	4.0	15	250	180	215	4.0	M12	200	130	165	3.5	M10
132 MB	2-6	132	178	216	262	12	590	327	89	38	80	41.0	10	12	300	230	265	4.0	15	250	180	215	4.0	M12	200	130	165	3.5	M10

* Subject to change without notice, exact dimension sheets on request.

5.5 Rotary pulse encoders

Motor attachment



Dimensions

	D1	D2	D3	L1	L2
NSE2-DIG-...	120	100	80	59.0	5.5
NSE5-DIG-...	140	115	95	65.0	12.0
NSE10-DIG-...	160	130	110	70.5	17.0
NSE25-DIG-...	160	130	110	98.0	19.0
NSE50-DIG-...	200	165	130	110.5	23.5
NSE100-DIG-...	200	165	130	142.0	25.0

Rotary pulse encoder DIG

An intelligent intermediate flange was developed, which significantly simplifies the recording of the rotational speed and direction of rotation and the linkage with super-ordinate control systems. This magnetic pulse transmitter is designed as an intermediate flange, which is simply installed between the motor and the motor adapter. This considerably simplifies the integration of incremental position transmitters in drive systems, regardless of whether they are used for rotational speed adjustment, as positioning controllers (e.g. for dosage control) or for synchronous run control.

Advantages

- Compact construction. Depending on the size, only 7 to 12 mm flange thickness are required in the installation space.
- Simple and fast assembly. The flange with the sensors is fixed directly on the motor; the magnetic ring is engaged on the motor shaft.
- Suitable for all IEC flange motors.
- A cost-effective solution, which is also suitable for economical retrofitting of existing drives.
- No mechanical changes necessary at the time of assembly.
- Proven, exact principle of measurement. Two Hall sensors pick up the signals for rotational speed and direction of rotation. As a result, the measurements are wear-free and maintenance-free.
- Universal HTL- and TTL signals for all the usual evaluations (PNP, NPN, RS 422).
- Short-circuit resistant, reverse polarity-protected and surge-protected transmitter electronics, in SMD-technology, completely integrated in the flange.

Mechanical values

max. rotational speed	6000 min ⁻¹
Temperature range, electronics	-40° C to 100° C at load ≤ 20 mA (120 °C at load ≤ 15 mA)
Temperature range, cable	-40° C to 80° C
Flange-/collar material	aluminium/steel
Connecting cable	PUR-jacket/4 x 0.25/ Ø 5 mm (TTL 6 x 0.14)
Cable length	Standard 2 m or upon request
Design with plug-in socket connection	plug 4-pole/cable length 5 m or 10 m (not for TTL -version)
Protection class	depends on the sealing between the motor flange and machine flange (max. IP 67 e.g. in case of sealing with silicon)
permissible vibration	100 m/s ²
permissible shock	1000 m/s ²

5.5 Rotary pulse encoder

Motor attachment

Flange	Shaft	Motor size	dxlength	ta	Da	Number of pulses						
						1	2	4	5	10	25	50
Ø120	Ø9	56	Ø9x20	2	63	x	x	x	x	x	x	
	Ø11	63	Ø11x23	2	63	x	x	x	x	x	x	
	Ø19	80	Ø19x40	2	63	x	x	x	x	x	x	
Ø140	Ø11	63	Ø11x23	2	85	x	x	x	x	x	x	x
	Ø14	71	Ø14x30	2	85	x	x	x	x	x	x	x
	Ø24	90	Ø24x50	3	85	x	x	x	x	x	x	x
Ø160	Ø14	71	Ø14x30	2	90	x	x	x	x	x	x	x
	Ø19	80	Ø19x40	2	90	x	x	x	x	x	x	x
	Ø24	90	Ø24x50	3	90	x	x	x	x	x	x	x
	Ø28	100	Ø28x60	3	90	x	x	x	x	x	x	x
Ø200	Ø19	90	Ø24x50	3	90	x	x	x	x	x	x	x
	Ø24	100	Ø28x60	3	90	x	x	x	x	x	x	x
	Ø28	112	Ø28x60	3	90	x	x	x	x	x	x	x

Other number of pulses on demand.

Example for ordering		
Type	Flange diameter	Shaft diameter
DIG	– 160 –	19 – 25

Electrical values

Voltage supply UB
Max. pulse frequency
Output signals

Pulse sequence

Pulse/Pause ratio
Signal level

Loading capacity
Insulation resistance

Insulation test
Short-circuit resistant

Secured against reverse polarity

Standard

10 to 24 VDC/+ 20%
20 kHz
rectangular pulse (2-channel) A + B

A 90° B Tolerance ± 40° el

180° : 180° Tolerance ± 20° el
Uhigh ≥ UB - 4 V at LLast ≤ 10 mA

≤ 30 mA at UB = 10 V resp.
≤ 20 mA at UB = 24 V

100 MΩ

4 kV

yes

yes

TTL-version

5 VDC/± 5%
20 kHz
rectangular pulse (2-channel)
A + B and A + B inv.

A 90° B Tolerance ± 40° el

A 90° B inv. Tolerance ± 40° el

180° : 180° Tolerance ± 20° el
Uhigh ≥ 3,5 V

Ulow ≤ 1 V Ulow ≤ 0,3 V

max. 30 mA of the outputs

100 MΩ

no

no

INKR Incremental rotary pulse transmitter



Mechanical properties, materials

Dimensions see drawing

Hollow shaft Ø 10 mm

Shaft load (axial and radial) 20 N max.

Flange Aluminium

Housing Anticorodal

Shaft Stainless steel, non-magnetic

Ball bearing ABEC 5

Electrical properties

Pulses 512,1024,2048

Operating voltage +10V +30V, +5V +30V

Outputs Push-Pull, Line Driver, PP/LD

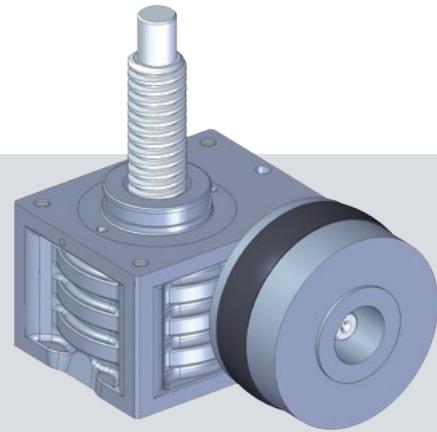
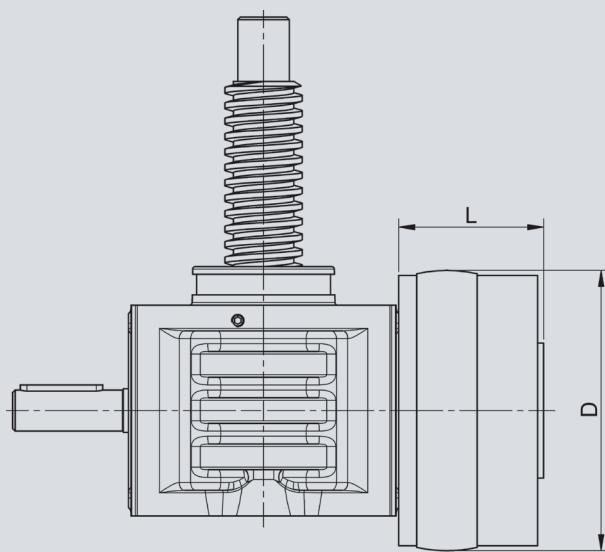
Loading per channel 40 mA max.

Counter frequency 100 kHz max.

Current drawn 70 mA max.

Optoelectric. Lifetime 100.000 h min.

Functional description



General

The spring-loaded brakes type FDB described here are dual-surface brakes for dry running. The braking torque is generated by compression springs in a current-less state. Venting takes place electronically by applying a DC voltage. Thanks to the guard rings that are used as a standard feature, the friction surfaces are mostly protected from external influences.

Under no circumstances may the friction surfaces come into contact with oil or grease or other lubricants.

Minor fouling of this kind can greatly reduce the braking torque. The protection class in the standard version is IP 54. The maximum permissible temperature is 145 °C; Duty cycle 100% ED.

Method of functioning

The existing compression springs press the brake rotor, which is positively locked with the gearbox shaft, against the flange via the axially movable ar-

mature disc. The braking torque is generated, applying a DC voltage to the exciter winding in the solenoid body results in a magnetic force, which pulls the armature disk towards the magnetic body. The brake rotor is released and the brake is vented.

Before working on an installed spring-loaded brake, the voltage supply source must always be disconnected or turned off. The brake should be rendered free of load if required, in order to avoid uncontrolled rotary motion of the shaft.

Manual venting

By providing a manual venting device (lever), the brake can be vented mechanically, e.g. in case of a power failure. For reasons of safety, nothing should be changed in the settings of the manual venting system.

Spring-loaded brake FDB

Design	Brakes-Type	T _B (Nm)	P (W)	Centres		
				Ø	L	D
NSE5	SL/RL	FDB 08	5.0	22	11	46 89
	SN/RN	FDB 08	5.0	22	11	46 89
NSE10	SL/RL	FDB 08	5.0	22	14	46 89
	SN/RN	FDB 10	10.0	28	14	54 109
NSE25	SL/RL	FDB 10	10.0	28	16	54 109
	SN/RN	FDB 13	20.0	34	16	62 135
NSE50	SL/RL	FDB 13	20.0	34	20	62 135
	SN/RN	FDB 15	40.0	42	20	69 155
NSE100	SL/RL	FDB 15	40.0	42	25	69 155
	SN/RN	FDB 17	60.0	50	25	81 175

T_B = braking torque

with direct current: P = U × I —————→ I = $\frac{P}{U}$

FDB60 at 205 V DC coil voltage

$$I = \frac{50W}{205V} = 0.24 A$$

Electrical Connection

There are half-wave and bridge rectifiers available for providing a power supply to the brakes from the AC supply. Both types are available for DC-side or AC-side connection. Owing to the inductance of the magnetic coil, the release of the armature disc after switching off takes place in a delayed manner. This switch-off delay is relatively long when connecting before the DC rectifier on the AC side. The switch-off delay can be reduced when the connections present at the rectifier are used for the DC-side switching (6x faster). If connections are to be made on the AC side, a bridge should be connected to the contacts. The electrical connections should only be made in a voltage-less state. The operating voltage (DC) of the brake is given on the magnet housing.

Maintenance

The load should be secured with a suitable support. The spring-loaded brakes are almost maintenance-free. The air gap «a» and hence the rotor wear must be checked at certain intervals of time and if required, reset, or the rotor must be replaced.

Re-adjusting the brake air gap

Loosen the 3 fastening screws of the brake through half a revolution. Now, the sleeve bolts, which surround the fastening screws, can be screwed into the magnet body by turning them counter-clockwise. With the 3 fastening screws, the magnet body is moved to such an extent in the direction of the armature disc, till the nominal air gap, see the table, is reached. Now, the 3 sleeve bolts are unscrewed out of the magnet body by rotating them clockwise till fixed contact is made. Next, the fastening screws are re-tightened and the air gap is once again checked with a feeler gauge.

Supply voltage	Operating voltage of the brake	Transformer rectifier / type
24V DC	24V DC	without
230V AC	105V DC	Half wave rectifier/KSE 500/1-S
230V AC	205V DC	Jumper rectifier/PMB 400-S
400V AC	180V DC	Half wave rectifier/KSE 500/1-S
500V AC	220V DC	Half wave rectifier/KSE 500/1-S

Brake size	FDB5	FDB10	FDB20	FDB40	FDB60
Air gap a_{nominal}	0.2	0.2	0.3	0.3	0.3
Air gap a_{max}	0.8	0.8	0.8	0.9	1.0
min. rotor thickness	4.5	5.5	7.5	9.5	11.5

Example for ordering

Size	Spring-loaded brake
	Nominal torque (TB)
	Operational voltage
	Direct current
	Rectifier package (if required)
	Manual venting (if required)
NSE10 FDB10 10Nm 205V DC GL HL	

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<p>Representations</p> <ul style="list-style-type: none"> ▷ Australie Mechanical Components P/L Phone +61 (0)8 9291 0000 Fax +61 (0)8 9291 0066 www.mecco.com.au mecco@arach.net.au ▷ Belgium Schiltz SA/NV Phone +32 (0)2 464 48 30 Fax +32 (0)2 464 48 39 www.schiltz-norms.be norms@schiltz.be Vansichen, Lineairtechniek bvba Phone +32 (0)1 137 79 63 Fax +32 (0)1 137 54 34 www.vansichen.be info@vansichen.be ▷ China Shenzhen Zhongmai Technology Co.,Ltd Phone +86(755)3361 1195 Fax +86(755)3361 1196 www.zmgear.com sales@zmgear.com ▷ Estonia Oy Mekanex AB Eesti filial Phone +372 613 98 44 Fax +372 613 98 66 www.mekanex.ee info@mekanex.ee 	<ul style="list-style-type: none"> ▷ Finland OY Mekanex AB Phone +358 (0)19 32 831 Fax +358 (0)19 383 803 www.mekanex.fi info@mekanex.fi ▷ Netherlands Stamhuis Lineairtechniek B.V. Phone +31 (0)57 127 20 10 Fax +31 (0)57 127 29 90 www.stamhuislineair.nl info@stamhuislineair.nl ▷ Norway Mekanex NUF Phone +47 213 151 10 Fax +47 213 151 11 www.mekanex.no info@mekanex.no ▷ Austria Spörk Antriebssysteme GmbH Phone +43 (2252) 711 10-0 Fax +43 (2252) 711 10-29 www.spoerk.at info@spoerk.at ▷ Spain tracsa Transmisiones y Accionamientos, sl Phone +34 93 4246 261 Fax +34 93 4245 581 www.tracsa.com tracsa@tracsa.com ▷ Czech Republic T.E.A. TECHNIK s.r.o. Phone +42 (0)54 72 16 84 3 Fax +42 (0)54 72 16 84 2 www.teatechnik.cz info@teatechnik.cz 	<p>TB 05/2015</p>